

Adaptive Terminal Sliding Mode Control For Nonlinear



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Adaptive Nonsingular Fast Terminal Sliding Mode Control ...

an adaptive nonsingular fast terminal sliding mode control scheme consisting of an adaptive control term and a robust control term for electromechanical actuator is proposed in this article. the adaptive control term with an improved composite adaptive law can estimate the uncertain parameters and compensate for the modelled dynamical ...

Direct Adaptive Terminal Sliding Mode Control For Lane ...

direct adaptive terminal sliding mode control for lane changing of vehicle doi: 10.9790/1684-1504052633 www.iosrjournals.org 28 | page where t_0 is the start time of lane

change, t_5 is the end time of lane change, and $t_1 t_0 t_5 t_4, t_2 t_1 t_4 t_3, t_3 t_2 2(t_1 t_0)$,

Adaptive Fuzzy Terminal Sliding Mode Control For A Class ...

adaptive fuzzy terminal sliding mode control for a class of mimo uncertain nonlinear systems v. nekoukar, a. erfania? neuromuscular control systems laboratory, iran neural technology research centre, department of biomedical engineering, iran university of science and technology (iust), tehran, iran

Adaptive Antisingularity Terminal Sliding Mode Control For ...

adaptive antisingularity terminal sliding mode control for a robotic arm with ... abstract: in this paper, a radical adaptive terminal sliding mode control method for a robotic arm with model uncertainties and external disturbances is proposed in such a way that the singularity problem is completely dealt with.

Adaptive Backstepping Terminal Sliding Mode Control Method ...

adaptive backstepping terminal sliding mode control method based on recurrent neural networks for autonomous underwater vehicle chao yang *,eng yao and m?jun zhang abstract the trajectory tracking control problem is addressed for autonomous underwater v(auv)ine envir?

Adaptive Terminal Sliding Mode Control For Rigid Robotic ...

4 robust adaptive terminal sliding mode control applying the terminal sliding mode control for rigid robotic manipulators needs the knowledge of the upper bound of uncertainties and disturbances in advance. how-ever, in the case of manipulators, the complexity and un-predictability of the structure of uncertainties may partic-

Proc ImechE Part G: Adaptive Nonsingular Terminal Sliding ...

terminal sliding mode control scheme is adopted to design the sliding surface. the switching gain is not necessary to be determined in advance but adjusted according to the adaptive rule.

Automatic Train Operation Based On Adaptive Terminal ...

adaptive terminal sliding mode control (atsmc) is a new idea proposed for ato control method, where a new termi-nal sliding surface is designed for sliding mode to trap the state trajectory to ensure the stability and robustness. to furtherensure the robustness, an adaptive control law is de-signed for dealing with the system uncertainties. it ...

Adaptive Fractional Integral Terminal Sliding Mode Power ...

keywords: adaptive fractional integral terminal sliding mode power control, doubly fed induction generator, multimachine power network, unified power flow controller 1 introduction the increase in the penetration of wind power, especially from doubly fed induction generator based wind farms into the existing power grids, is although beneficial, but

